



Powering Innovation That Drives Human Advancement

---

# **Ansys ConceptEV**

Client Presentation

# Agenda



*“Optimize your powertrains and your teams!”*

01 – CHALLENGES

---

02 – SOLUTION

---

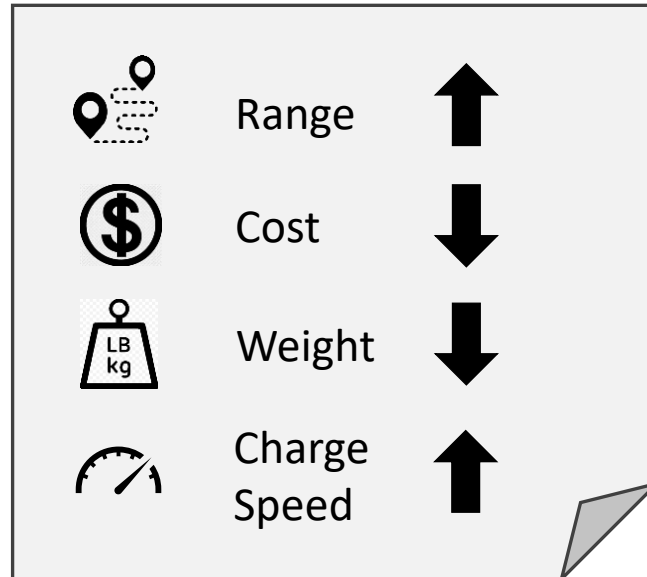
03 – CASE STUDY

---

# Challenges

- ❑ Intense global competition in the automotive industry to develop the best EV powertrain & gain market share
- ❑ Efficiency is one of the key design goals

Better efficiency



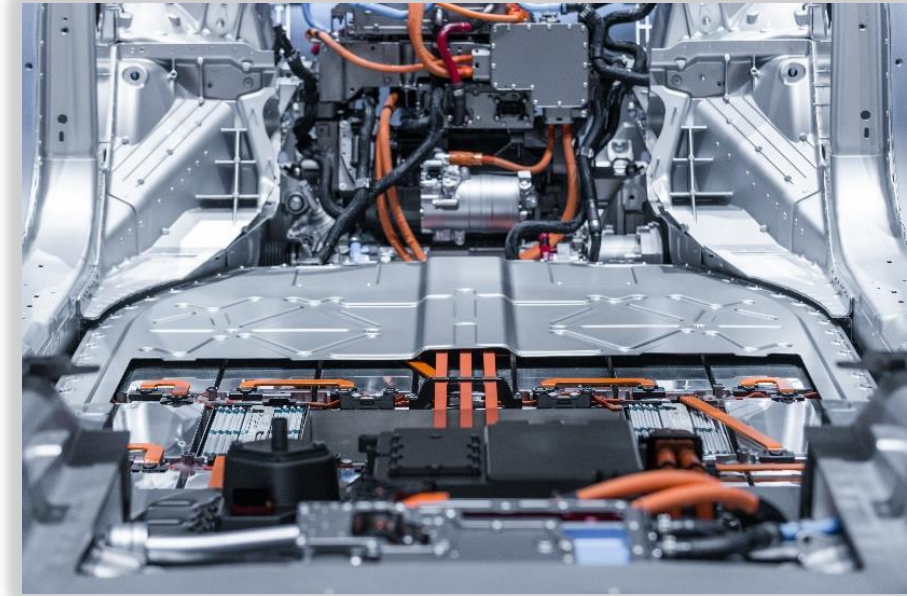
# Challenges

- ❑ To create the highest performance powertrain, the components must be optimized together – as an interconnected system

**Individually Optimized  
Components**  
[ motors + inverters +  
batteries + transmissions ]

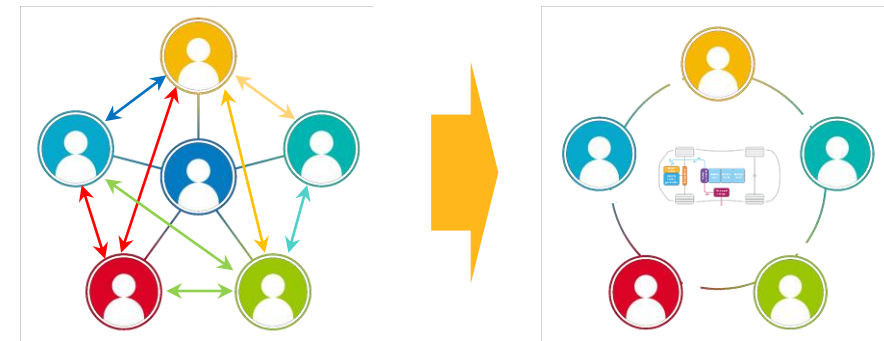
≠

**Optimized  
System**

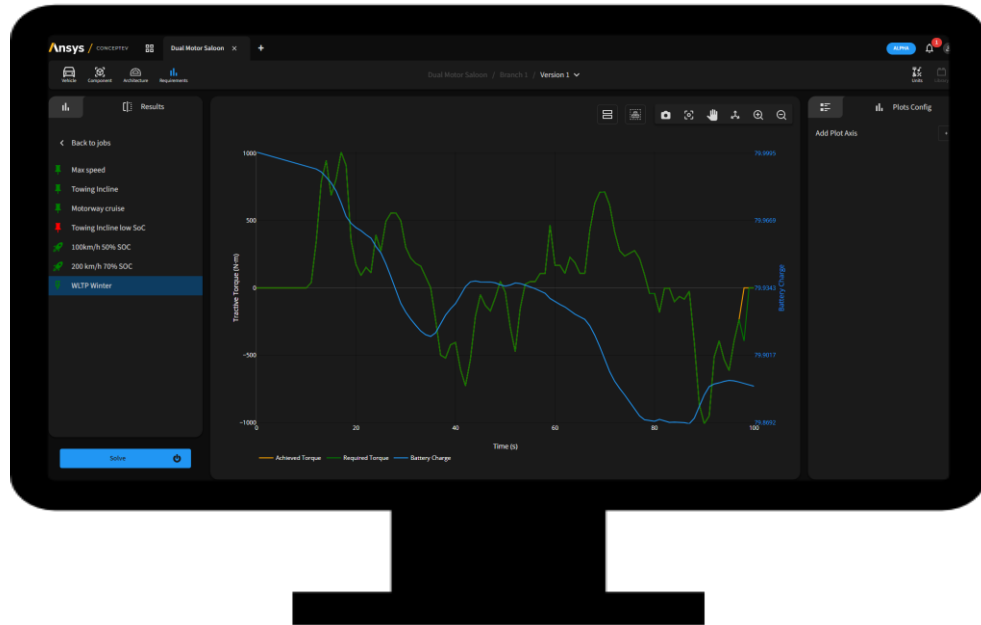


## How?

- ❑ System level analysis & metrics in the component design loop
- ❑ Democratized & shared system level model (collaborative)
- ❑ System analysis in the early design phase



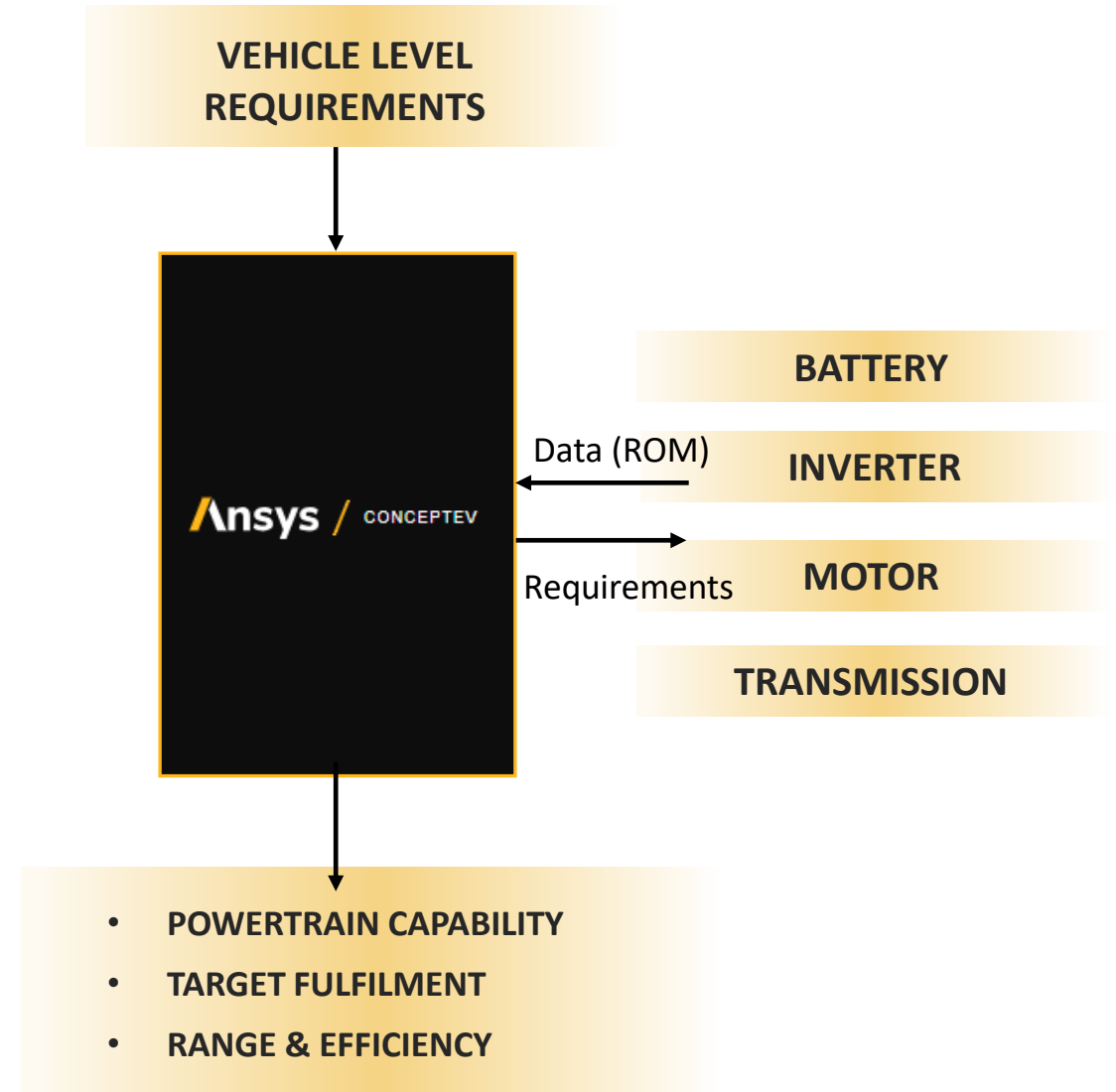
# Solution



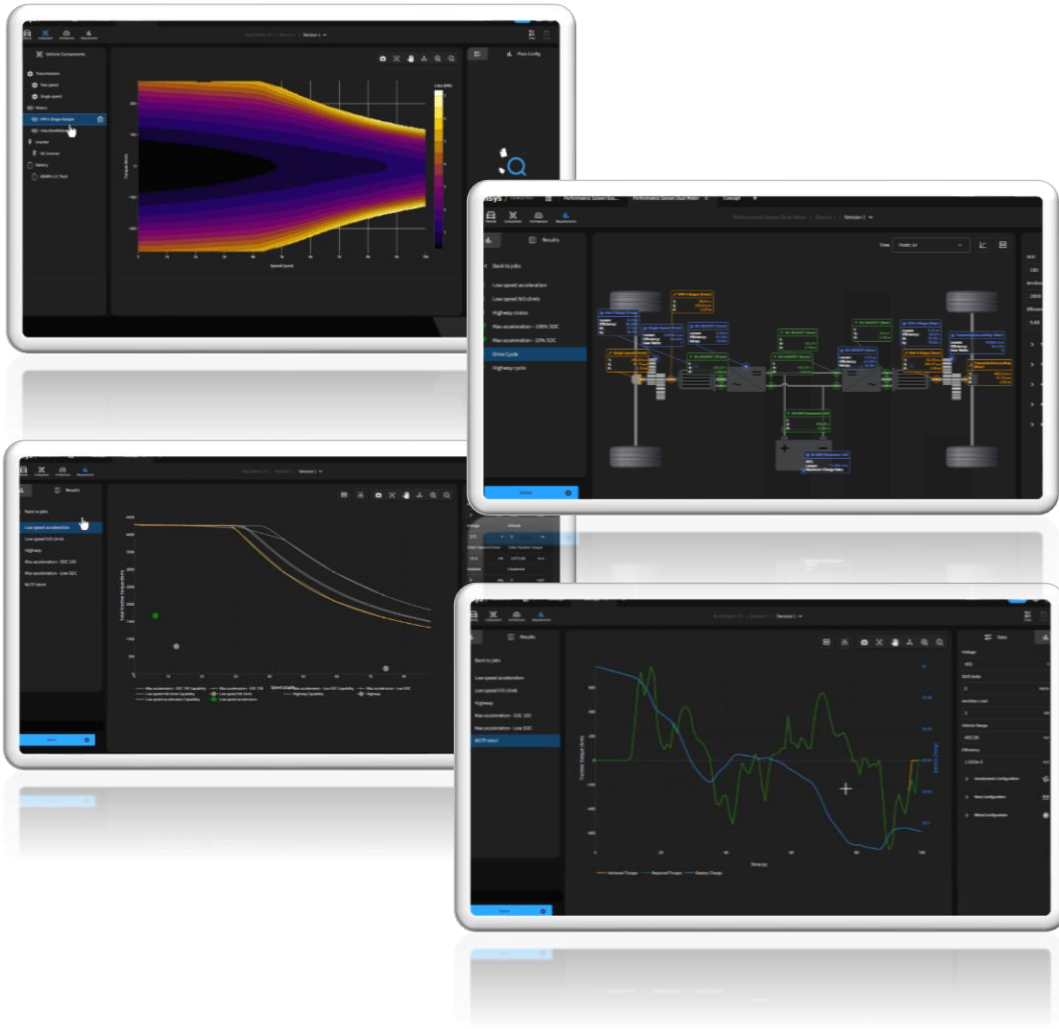
- ❑ Ansys ConceptEV is a cloud-based design & simulation platform for the concept design of EV powertrain
- ❑ System & Component Design engineering teams can collaborate on a shared system simulation connected to requirements from the start of the design process

# Solution

- ❑ Create model & add collaborators
- ❑ Import component models
- ❑ Connect components in powertrain architectures
- ❑ Add system level requirements
- ❑ Simulate the system with embedded control strategies
- ❑ Evaluate performance against requirements
- ❑ Assess metrics over drive cycles (e.g. range, efficiency)



# Solution



- ❑ Model-based approach to optimizing the powertrain system & components.
- ❑ Rapid evaluation of different powertrain configuration & component design choices
- ❑ Data-driven decisions are made early in the design process.
- ❑ Shared system model empowering teams to share their knowledge & insights
- ❑ Simple set-up with minimum data required
- ❑ Scalable for increasing demand, complexity & number of users

# Ansys ConceptEV – Demo

The screenshot displays the Ansys ConceptEV software interface for a 'Performance Saloon Dual Motor' vehicle. The main workspace shows a schematic of the vehicle's drivetrain, including two front wheels, two rear wheels, a central battery pack, and two electric motors (front and rear). Each component is annotated with a data box providing performance metrics.

**Component Data:**

- IPM V-Shape (Front):** Losses: 0.14 kW, Efficiency: 90.35%, Id: -17.18 A, Iq: 50.37 A
- Single Speed (Front):** Losses: 4.89e-2 kW, Efficiency: 96.16%, Gear Ratio: 7
- SIC MOSFET (Front):** Losses: 0.38 kW, Efficiency: 78.79%, Vdrop: 16.68 V
- SIC MOSFET (Rear):** I: 432.4 V, V: 432.4 V, P: 2.78 kW
- SIC MOSFET (Rear):** Losses: 0.57 kW, Efficiency: 83.03%, Vdrop: 16.86 V
- IPM V-Shape (Rear):** Losses: 0.32 kW, Efficiency: 88.6%, Id: -35.66 A, Iq: 76.65 A
- TransmissionLossMap (Rear):** Losses: 4.66e-2 kW, Efficiency: 98.11%, Gear Ratio: 8
- 80 kWh Panasonic Cell:** SOC: 7.13e-3, Losses: 7.13e-3 kW, Maximum Charge Rate: [unspecified]

**Results Sidebar (Left):**

- Back to jobs
- Low speed acceleration
- Low speed hill climb
- Highway cruise
- Max acceleration - 100% SOC
- Max acceleration - 20% SOC
- Drive Cycle** (Selected)
- Highway cycle

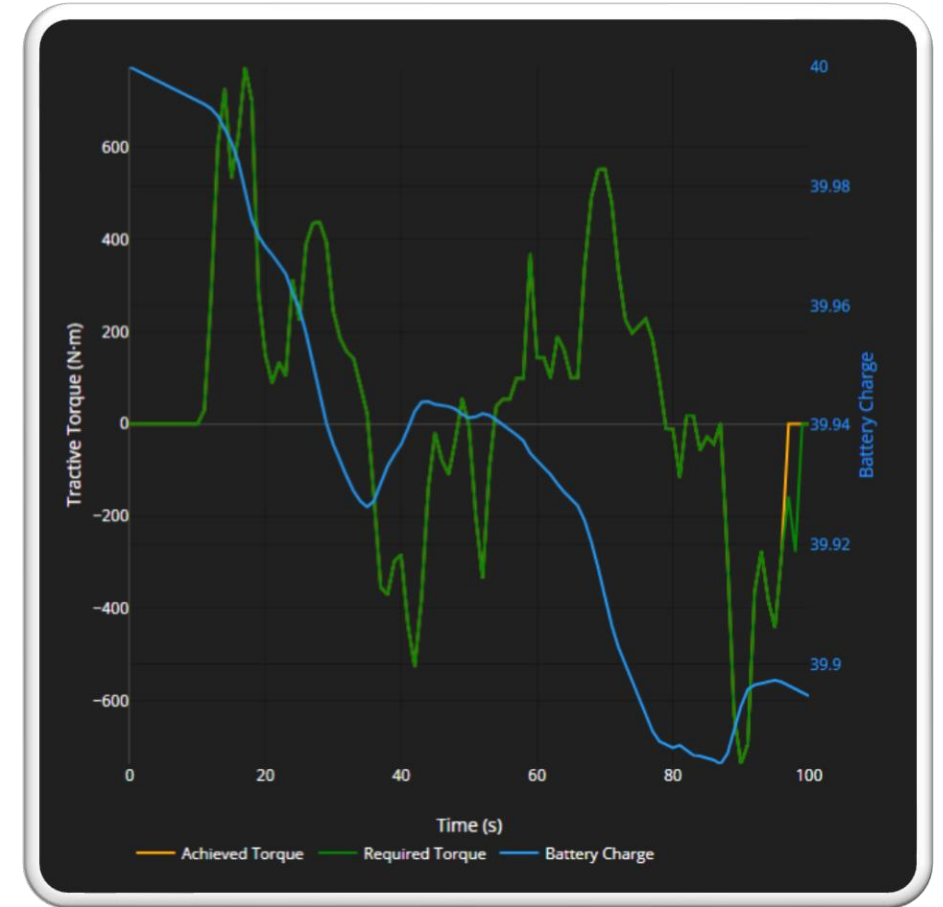
**Data Panel (Right):**

- SOC: 100 %
- Shift Delta: 0 kWh
- Ancillary Load: 2000 W
- Vehicle Range: 452.95 km
- Efficiency: 5.66 km/kWh
- Totals
- Total Losses by Component
- Aerodynamic Configuration
- Mass Configuration
- Wheel Configuration



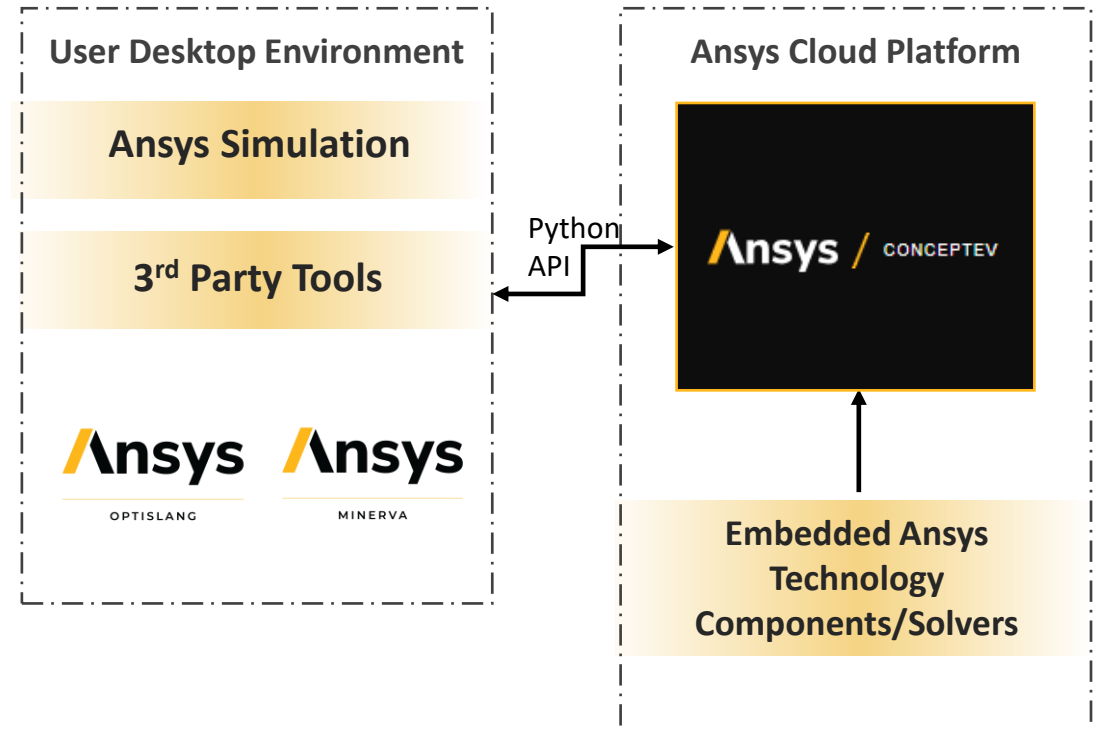
# Ansys ConceptEV – Simulation Methodology

- Iterative electrical system solve based off equivalent circuit parameters
  - Voltage at motor terminal function of battery + harness + inverter losses & voltage drops
  - System voltage function of battery SoC (varies across cycle)
- Multi-state analysis & optimization at each time step:
  - Motor(s) control  $I_d/I_q$
  - Power split between EDUs
  - Gear selection (function of state in previous time step)
- Evaluation of operating states for requirement evaluation:
  - Max capability from component limits
  - Max regen from battery limits
  - Max efficiency mode



# How is Ansys ConceptEV Connected and Automated?

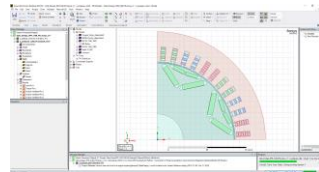
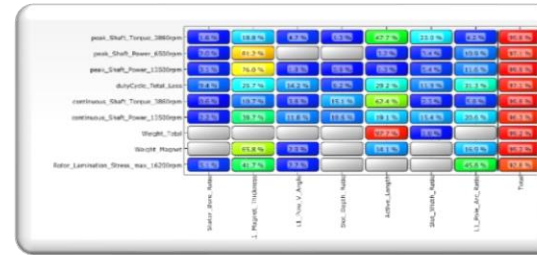
- ❑ Open interfaces for connection with Ansys or 3<sup>rd</sup> party tools
- ❑ Python API for automated workflows
- ❑ Can use optiSLang to drive design space exploration studies



# Example of Component Optimization at System Level

System level optimization solution for electric machines

Design parameters



CONCEPTEV



Automated ROM

Vehicle level requirements ✓  
✗

Range

Efficiency

# Differentiators of Ansys ConceptEV



- ✓ Bespoke design & simulation platform for EV powertrains with in-built control



- ✓ Quickly & simply perform design space exploration against requirements on a shareable platform



- ✓ Open & accessible to cross-functional teams enabling enhanced communication & model exchange

# Case Study: Example of an Automotive OEM



## CURRENT SCENARIO

## CONCEPTEV SCENARIO

Internal solution with mixture of commercial system simulation tools & in-house development



*Fully supported simulation evaluation tool integrated with existing component design workflows*

Vehicle attributes broken down into specification of sub-system – requirements cascade



*More comprehensive data driven design space exploration in early phase*

Overspecification of sub-systems



*Optimized powertrain design trade-offs*

Siloed organization



*Shareable within & across the organization*

Specialist system tools owned by few people – closed access



*All stakeholders work around the same data/tool*

# Case Study: Example of an Automotive OEM



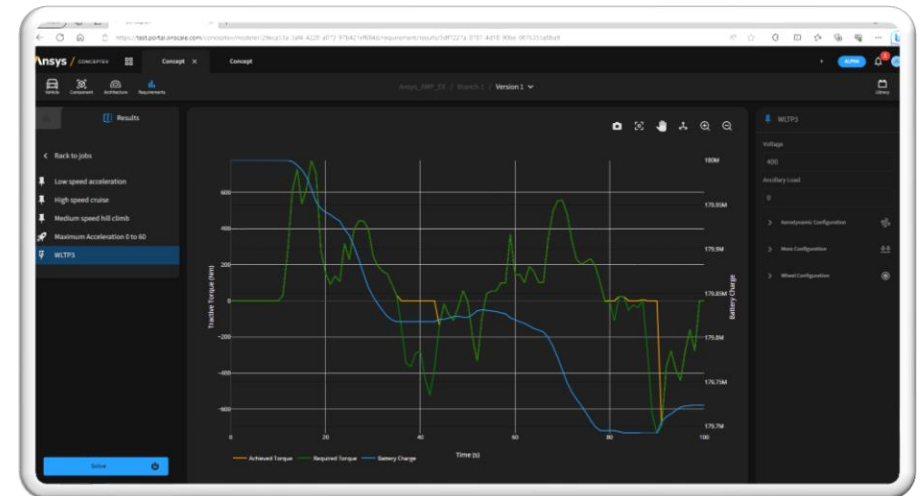
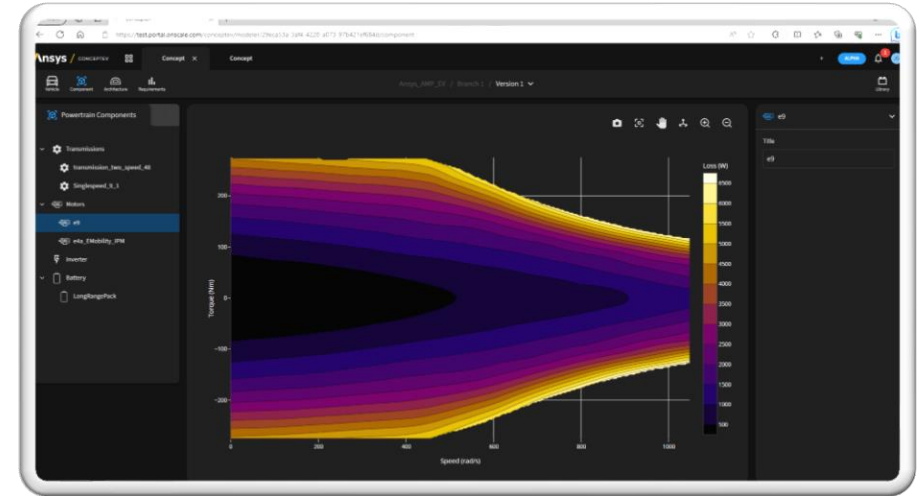
- ✓ Better system design decisions
- ✓ Better management decisions due to visibility
- ✓ Lowered technical & commercial risks
- ✓ Increased human understanding of design space
- ✓ Reduced # of design iterations
- ✓ Higher quality concept design – traceable & open
- ✓ Fully engaged stakeholders
- ✓ Cross-functional teams working from the same data sets



- Accelerate time to market (more NPIs)
- Produce more competitive powertrain design
- Achieve cost target
- Save time & boost innovation

# Summary

- ❑ ConceptEV is an innovative new cloud native tool developed by Ansys for the design & optimization of electrified powertrains.
- ❑ It enables early-stage evaluation and optimization of powertrain configurations.
- ❑ Through the cloud interface, teams can collaborate & exchange data to ensure system trade-offs are integrated into component design decisions.



The Ansys logo consists of a yellow slanted bar followed by the word "Ansys" in a bold, black, sans-serif font.





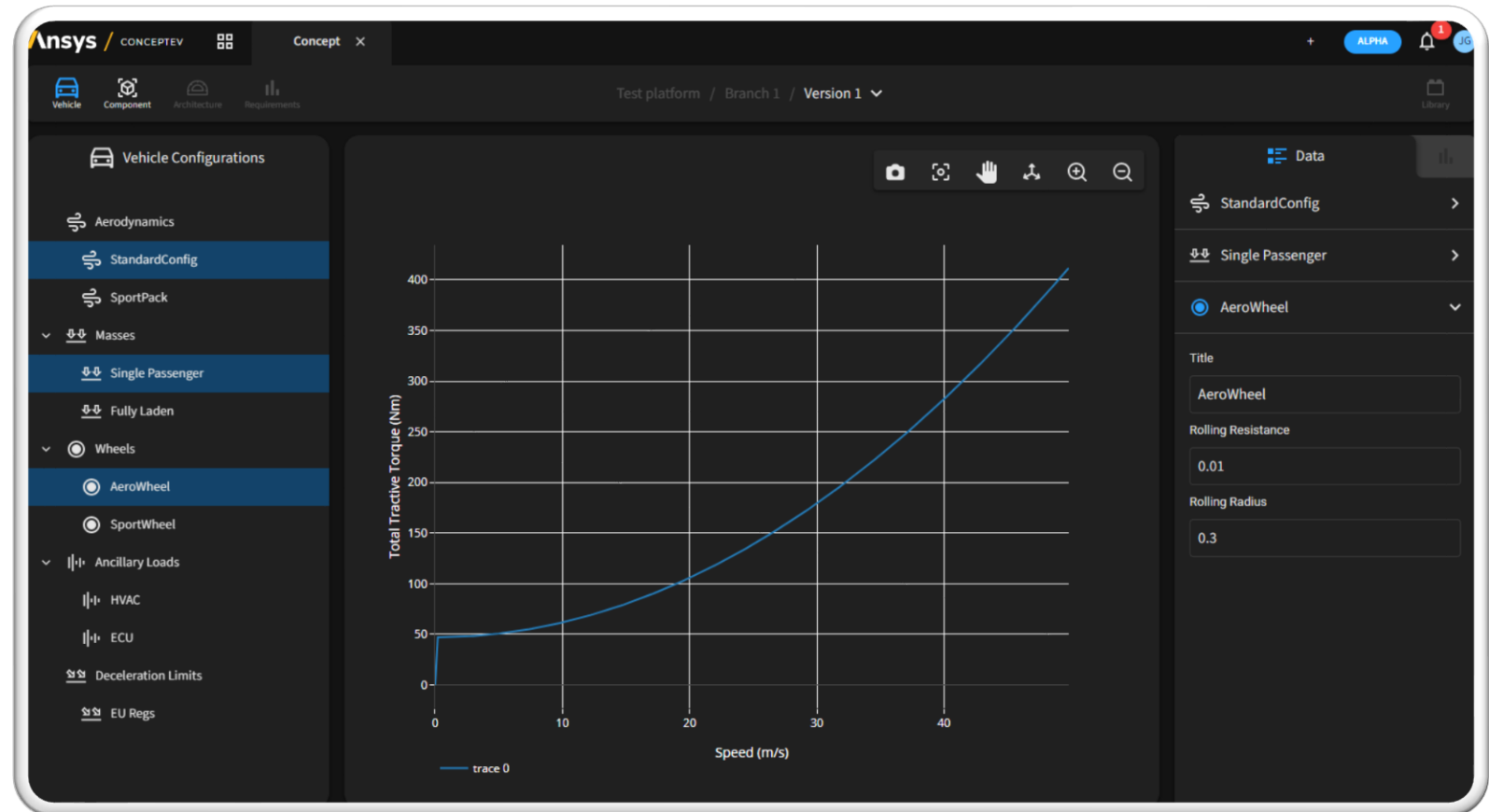


# Additional Slides

More About the Interface - Demo

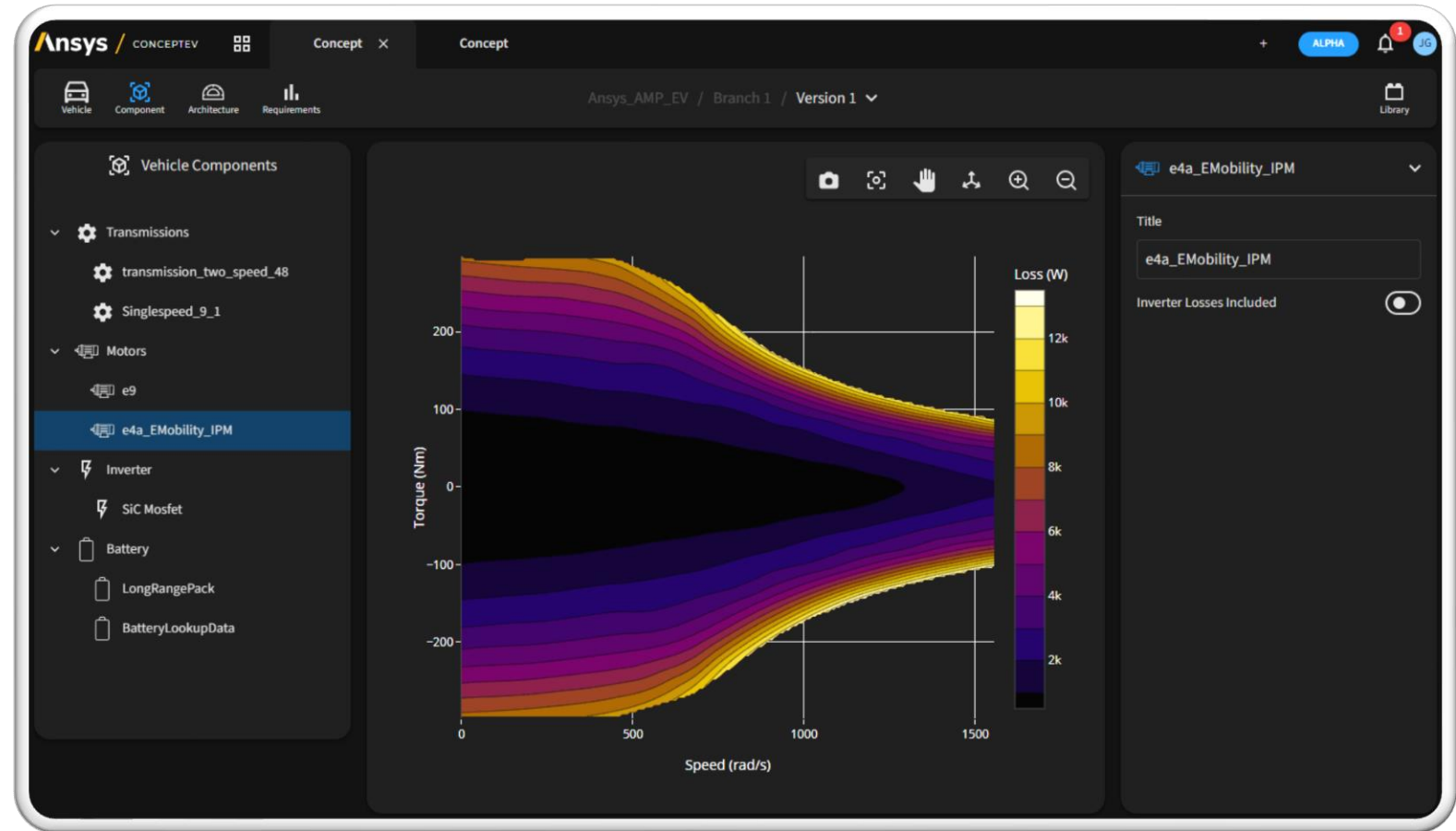
# Ansys ConceptEV Preview – Vehicle Model

- Vehicle mode: multiple aero, mass, wheel, and stability configurations defined

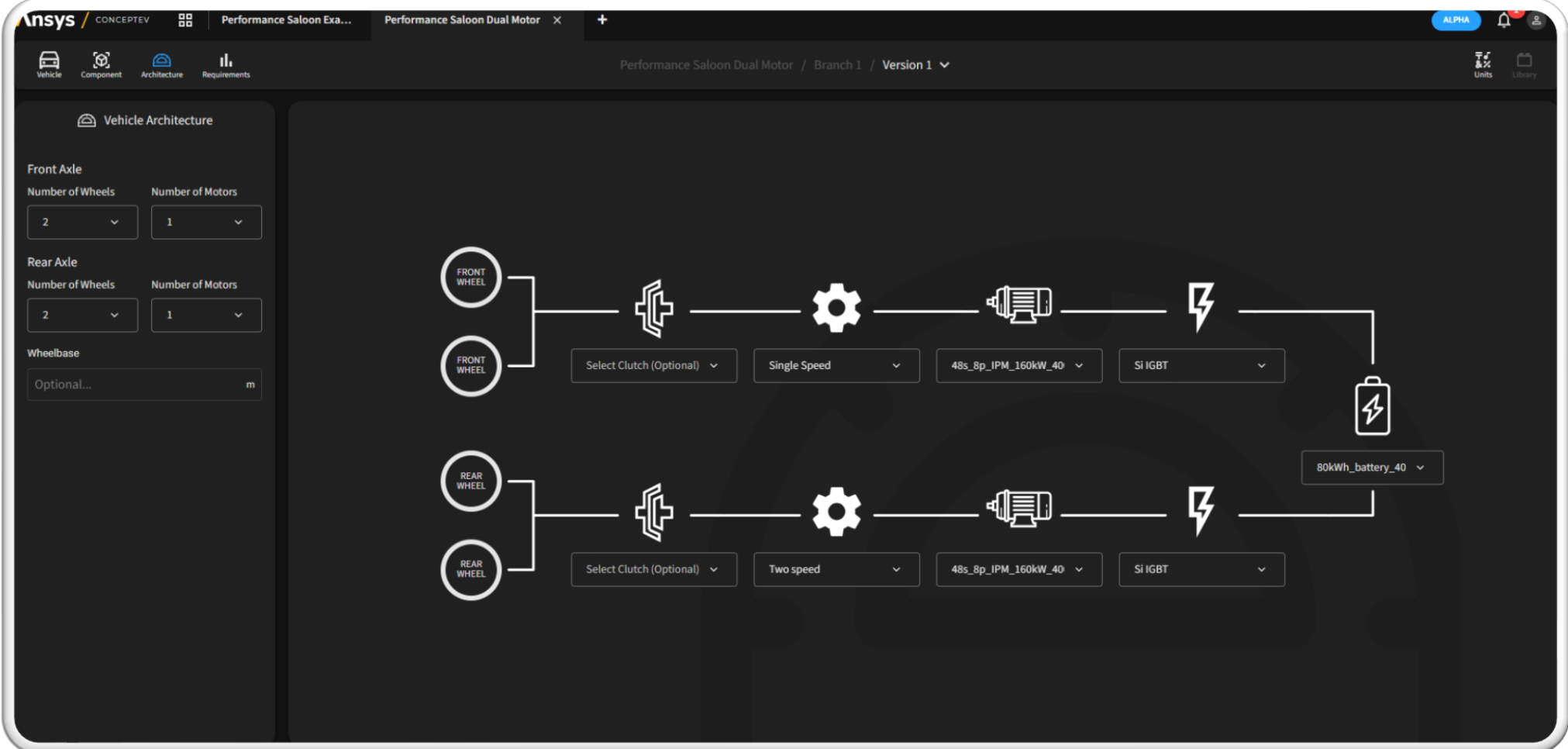


# Ansys ConceptEV Preview – Component Model Connections

- ❑ Electric machine, Inverter, transmission, battery models/data connected
- ❑ Range of different model fidelity options for each component
- ❑ Automated interfaces are built from component tools (e.g. Ansys Motor-CAD)
- ❑ Many components can be defined

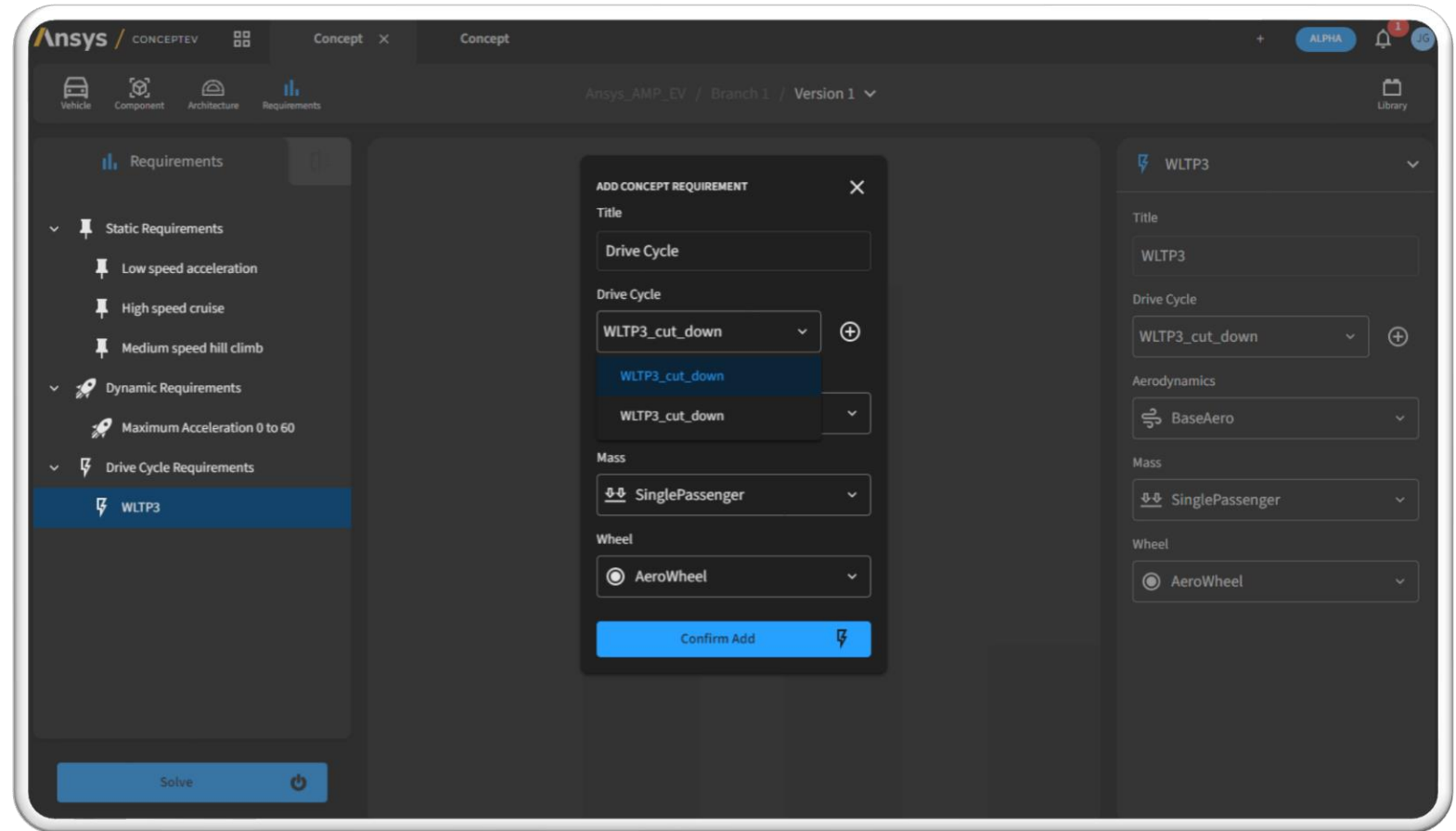


# Ansys ConceptEV Preview – Component Model Connections



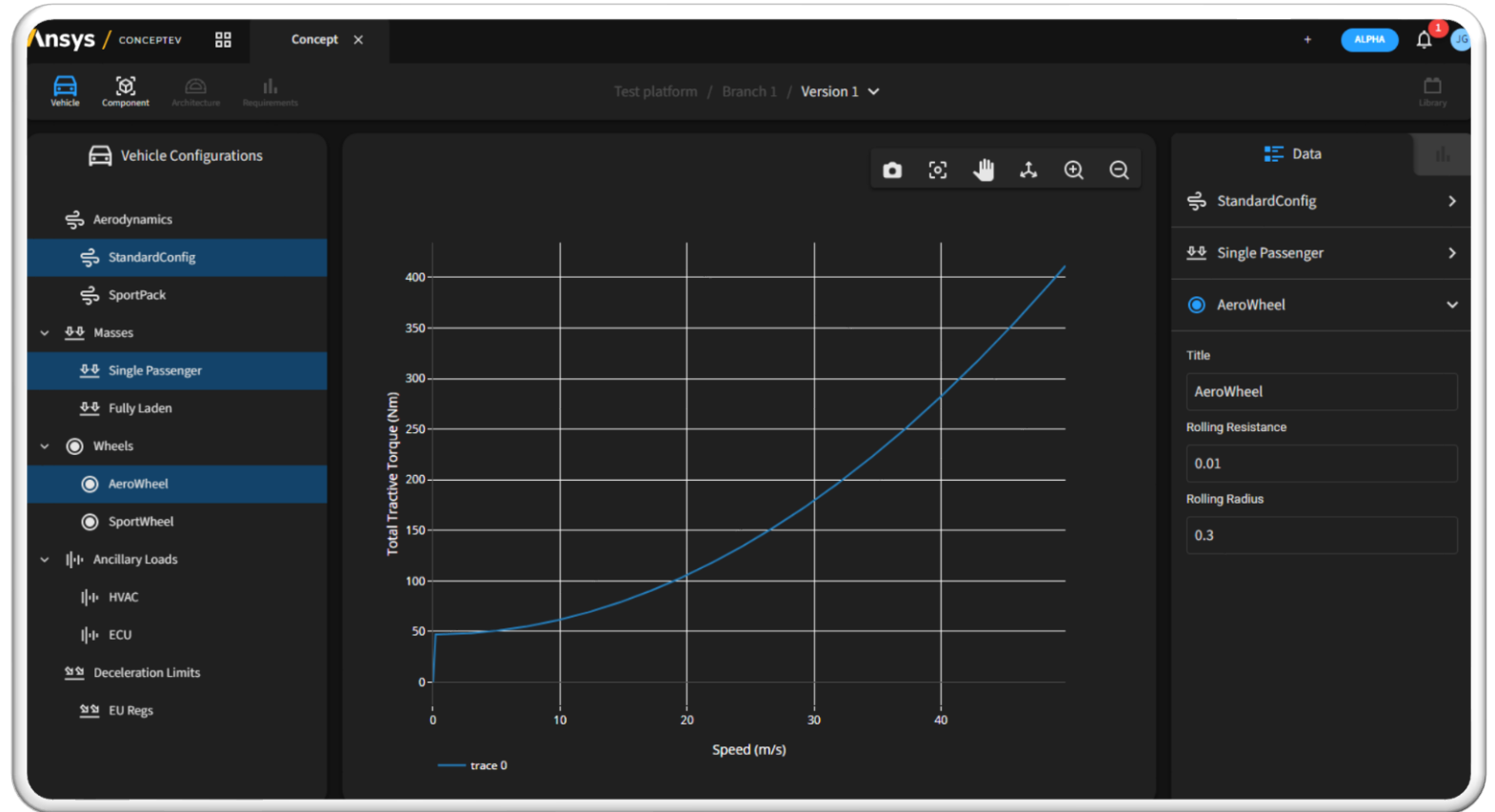
# Ansys ConceptEV Preview – Requirements

- ❑ Vehicle level requirements are specified or imported
- ❑ The powertrain performance is simulated with in-built control strategies to evaluate which of these requirements can be achieved



# Ansys ConceptEV Preview – Energy

- Drive cycles are performed to evaluate energy consumption & vehicle range
- Control strategies applied:
  - Power splits between drive units
  - Shifting strategies
  - Variable battery voltage with state-of-charge
  - Battery charge acceptance limits in regen
  - Vehicle stability deceleration limits using regen



# EDU Requirements

## What if we only receive the EDU level requirements, not those of the vehicle?

- ❑ ConceptEV will provide an EDU model where you can:
  - Define EDU level requirement list
  - Simulate EDU behavior against requirements
  - Control  $I_d/I_q$  with combined inverter & motor behavior, efficiency & voltage
  - Model multi-speed transmissions
- ❑ To consider:
  - How are the EDU level requirements derived? Particularly with multiple driven axles
  - Could ConceptEV be used to change the paradigm on how component design interfaces with the system integrators? Could this lead to a competitive advantage in the development of the powertrain?

